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## Rockhound v3.16, v3.17

Antelope/Kinematics User's Group

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# Rockhound v3.16

v3.16 released October 2018

- GUI & usability improvements
- MBB2 support
- Ring Buffer reliability changes
- Various changes in support of OASIS & Q330 family
- General stability changes and fixes



# GUI and Usability<sup>1</sup>

Segmented controls and toggles to reduce the needed number of clicks

## v3.15

Filter Type at 1sps	?	acausal ▼	All
Filter Type at 10sps	?	acausal ▼	All
Filter Type at 20sps	?	acausal ▼	All
Filter Type at 50sps	?	acausal ▼	All
Filter Type at 100sps	?	acausal ▼	All
Filter Type at 200sps	?	acausal ▼	All

## v3.16

Filter Type at 1sps	<input checked="" type="checkbox"/> acausal <input type="checkbox"/> causal	?
Filter Type at 10sps	<input checked="" type="checkbox"/> acausal <input type="checkbox"/> causal	?
Filter Type at 20sps	<input checked="" type="checkbox"/> acausal <input type="checkbox"/> causal	?
Filter Type at 50sps	<input checked="" type="checkbox"/> acausal <input type="checkbox"/> causal	?
Filter Type at 100sps	<input checked="" type="checkbox"/> acausal <input type="checkbox"/> causal	?
Filter Type at 200sps	<input checked="" type="checkbox"/> acausal <input type="checkbox"/> causal	?

# GUI and Usability<sup>2</sup>

Segmented controls and toggles to reduce the needed number of clicks

## v3.15

Temperature Stream	?	true ▼
Humidity Stream	?	true ▼
VofV12Batt Stream	?	true ▼
VofSysPwr Stream	?	true ▼
IofSysPwr Stream	?	true ▼

## v3.16

Temperature Stream	<input checked="" type="checkbox"/>	?
VofSysPwr Stream	<input checked="" type="checkbox"/>	?
IofSysPwr Stream	<input checked="" type="checkbox"/>	?
TimeQual Stream	<input checked="" type="checkbox"/>	?
BTP TimeQual Stream	<input type="checkbox"/>	?

# MBB-2 & Sensors

Specific support for MBB-1 & 2

## Sensor Control

Channel sensor groups Grp1	EpiSensor	All	?
Time Source	EpiSensorFS-SS1		?
	EpiSensorFS		?
GNSS Source 1	FBA11		?
	FBA13		?
	FBA23		?
GNSS Source 2	FBAFS		?
	GENBBFS		?
GNSS options	MBB1SineFS		?
	MBB1SineFSwTF		?
	MBB1SweptFS		?
Internal Deck	MBB1SweptFSwTF		?
	MBB2SineFS		?
Low Latency	MBB2SineFSwTF		?
	MBB2SineNoAttFS		?
	MBB2SineNoAttFSwTF		?
DFS sample rate	MBB2SweptFS		?
	MBB2SweptFSwTF		?
DFS Mode	PBBFS		?
	PBBFSwTF		?
Alarm Duration	SS1FSwTF		?
	0		?

## Sensor Types

dig1 Ch1 Sensor Type (Physical)	32	All	?
dig1 Ch2 Sensor Type (Physical)	32	All	?
dig1 Ch3 Sensor Type (Physical)	32	All	?
dig1 Ch4 Sensor Type (Physical)	32	All	?

10.0.3.78 says

Sensor Type index for the physical channel (10=FBA-11, 11=FBA-4g, 12=FBA-2g, 13=FBA-1g, 14=FBA-0.5g, 15=FBA-0.25g, 16=FBA-0.1g, 20=FBA-23, 30=WR-1, 32=EpiSensor, 33=S6000, 34=Mark L22, 35=Mark L4C, 36=CMG, 37=CMG3T, 38=CMG40T, 39=CMG5, 40=KS-2000, 41=GT-S13, 42=CMG3ESP, 43=KMI-SH1, 44=KMI-SV1, 50=PBB, 51=MBB-1, 52=MBB-2, 60=STS-1, 61=STS-2, 62=STS-2.5, 63=STS-3, 66=STS-5A, 67=STS-6A) - needed for EVT, SAC and COSMOS files (Physical)

OK

# Ring Buffer

Fixes specific to the Ring Buffer

- Remove sync from RBServer arrival that could help avoid FrontEnd watchdogs related to an orb2orb restart talking to a digitizer with a large ring buffer.
- Corrected problems with potential loss of RB data stream sync if ORB packet messages were sent on an open connection that was currently performing a reap. Traffic from the packet response could momentarily corrupt the traffic from the reap – although the original data in the ring buffer was itself not affected.
- Corrected problems with the RingBuffer server that could very rarely cause it to get "stuck" at the buffer wraparound point. Also fixed problems with long reject strings being too large for the fixed size return packet.

# Rockhound v3.17

Slated for release late 2019

- New PoC mechanism
- Layout Differences page
- UpdateMonitor supports ssh
- Bit weight in g
- Station XML for configuration upload/download
- Potential additions:
  - Multiplexed ORB packets



# PoC Mechanism<sup>1</sup>

New PoC mechanism based on JSON packets

POC Client		
POC Server Address	<input type="text" value="10.0.3.136"/>	<input style="border: none; background-color: #ccc; padding: 2px 5px; font-size: 12px; font-weight: bold; text-align: center; width: 20px; height: 20px;" type="button" value="?"/>
Port Number	<input type="text" value="9300"/>	<input style="border: none; background-color: #ccc; padding: 2px 5px; font-size: 12px; font-weight: bold; text-align: center; width: 20px; height: 20px;" type="button" value="?"/>
Use JSON Packets	<input checked="" type="checkbox"/>	<input style="border: none; background-color: #ccc; padding: 2px 5px; font-size: 12px; font-weight: bold; text-align: center; width: 20px; height: 20px;" type="button" value="?"/>
POC Interval	<input type="text" value="120"/>	<input style="border: none; background-color: #ccc; padding: 2px 5px; font-size: 12px; font-weight: bold; text-align: center; width: 20px; height: 20px;" type="button" value="?"/>
Connections Required	<input type="text" value="9500:1"/>	<input style="border: none; background-color: #ccc; padding: 2px 5px; font-size: 12px; font-weight: bold; text-align: center; width: 20px; height: 20px;" type="button" value="?"/>

**POC Client module.** Runs in a digitizer to broadcast unit's unique ID and outside IP address to a data center

**POC Server Address:** Space separated list of POC server addresses to receive broadcasts. Blank if unused. The POC Client will periodically connect to the POC Server(s) at these addresses to communicate this unit's information and outside IP address.

**Port Number:** TCP Port for POC server connection

**Use JSON Packets:** Use JSON packets for communication with the POC host, else uses legacy KMI POC format

**POC Interval:** Interval in seconds for POC broadcasts. See Connections Required.

**Connections Required:** Stop sending POC messages when connected. This is a space separated list of required connections. Each entry is a port number and a number of connections. Example 9500:2, meaning 2 connections on port 9500. If connections not met or parameter is blank, then POC messages will continue to be sent at the specified interval

# PoC Mechanism<sup>2</sup>

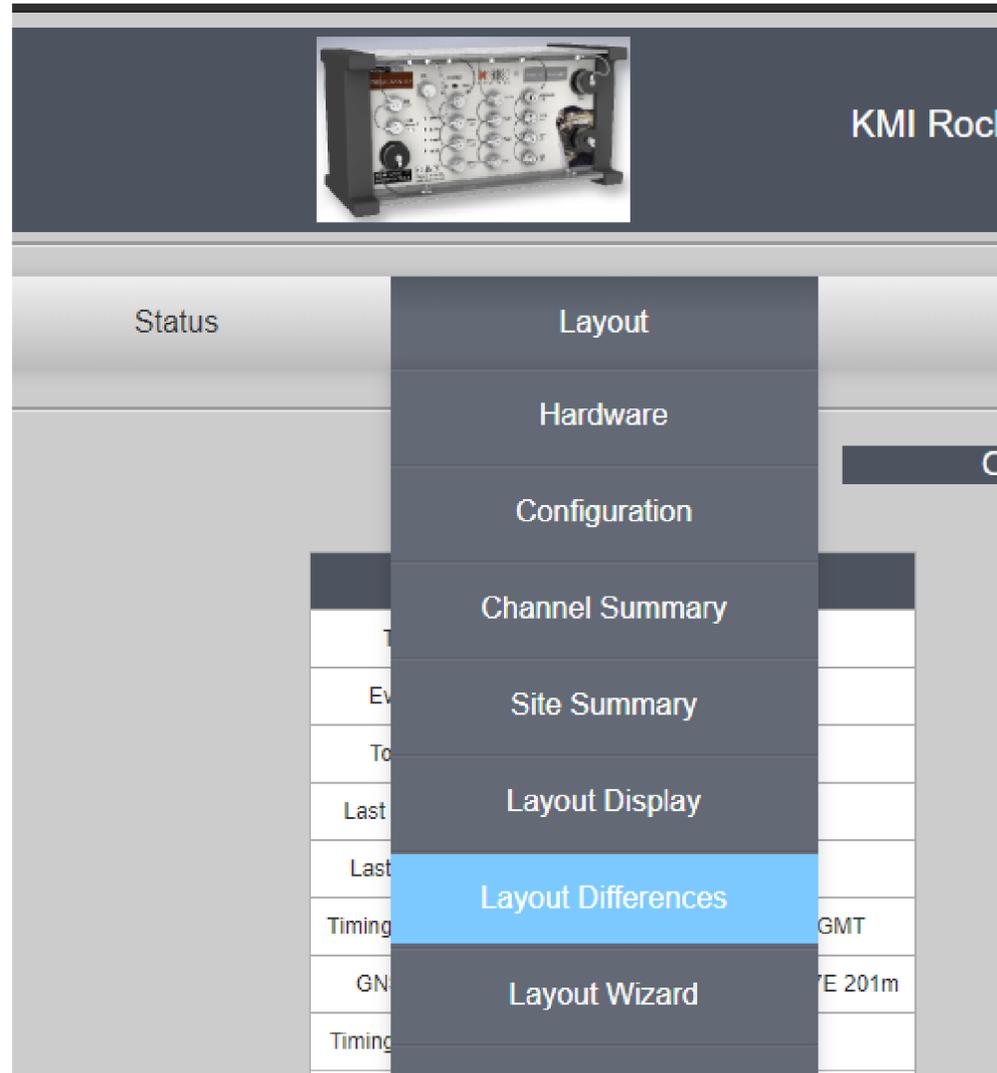
Content of the JSON packets

```
{  
  "CREATED_ON":"2019-04-23T15:59:10Z",  
  "UNIT_TYPE":"ETNA2",  
  "ESN":"E52988XXXXXXXXXX",  
  "TAG":"3",  
  "STATION":"ETNX",  
  "NETWORK":"KM",  
  "SYSTEM_STARTED":"2019-04-23T15:50:03Z",  
  "TIMING_TYPE":"GNSS",  
  "TIMING_QUALITY":"100.0%",  
  "LATITUDE":"34.150109N",  
  "LONGITUDE":"-118.101093E",  
  "ELEVATION":"248M",
```

```
  "PORT_CONNECTIONS": [  
    { "PORT":0, "EXPECTED":0 }  
  ]  
  "POCS_NOTIFIED": [  
    { "HOST":"10.0.3.136" }  
  ]  
  "RH_VERSION":"V3.16.1S PRE-RELEASE",  
  "HASH":"6E6982921171F2ADAD7239EE3971AD6B"  
}
```

# Layout Differences

Overview of configuration differences from factory setup



Layout	Files	Triggering	
<b>Layout Differences</b>			
Differences From Factory Configuration			
<b>Modules Removed</b>			
Status Server		?	
<b>Modules Added</b>			
Aged Auto File Delete		?	
Rock Monitor Client		?	
Summary File Generator		?	
<b>Module Parameters</b>			
<b>Parameter</b>	<b>Factory</b>	<b>Active</b>	<b>?</b>
<b>Waveform viewer</b>			
Real-time FFT and PSD	false	true	?
<b>dig1, Rock2 Data Interface</b>			
Low Latency	false	true	?
VoV12Batt Stream	true	false	?
Mass Position Stream	false	true	?
Mass Position Stream	false	true	?
Mass Position Stream	false	true	?
Max SPS (Advanced)	200	5000	?

# UpdateMonitor ssh

Allow UpdateMonitor access via ssh

Update monitor		
Scan frequency	?	1
Update server	?	10.0.3.136
Use ssh	?	<input checked="" type="checkbox"/>
ssh port number	?	22
Update user	?	dpumphrey
Base directory	?	updates
Passive mode	?	<input type="checkbox"/>

**Monitors a system input directory watching for updated firmware and/or configuration information to be loaded to the unit.**

**Scan frequency:** Frequency to check for remote configuration or firmware updates, in hours. If remote updates are enabled, parameter and firmware updates will also be checked for remote updates at this interval. Set the interval to zero to disable remote updates.

**Update server:** Remote update server. e.g.: myserver.com or 10.0.0.1. Set this parameter blank to disable remote updates, or set it to the server that will contain firmware and configuration updates.

**Use ssh:** Use ssh rather than FTP when true. If false, use FTP.

**ssh port number:** Port number for ssh connections. Typically port 22.

**Update user:** Remote update user for login to the update server, e.g.: fred

**Update password:** Remote update password for login to the update server, e.g.: mypassword

**Base directory:** Base directory for where to get files on the update server, e.g.: pub/incoming

**Passive mode:** Passive FTP mode, to be used when FTP server does not support active mode

# Bit Weight in g

Reports the bit weight of each channel on the channel summary page

Channels and Sensors							
VCh	Id	SPS	Sensor Type	Full Scale	Sensitivity	G Range	Bit Weight
1	C1	100	32: EpiSensor [a]	20.0V	10.0V/g	2g	0.23841858ug
2	C2	100	32: EpiSensor [a]	20.0V	10.0V/g	2g	0.23841858ug
3	C3	100	32: EpiSensor [a]	20.0V	10.0V/g	2g	0.23841858ug
4	C4	100	32: EpiSensor [a]	20.0V	10.0V/g	2g	0.23841858ug

# Station XML

Station configuration accepted as XML or JAR files

## Administrative Details

[Click Here to download parameters \(as JAR\).](#)

[Click Here to download parameters \(as XML\).](#)

- System's configuration presented in both forms
- Edited XML can be uploaded same as "config.jar" files
- XML can be served by remote UpdateMonitor server

```
<?xml version="1.0" encoding="iso-8859-1" ?>

<!-- Rockhound configuration -->
<!-- File /usr/rock/SMARTSDist/config/config.xml -->
<!-- Written 2019/04/30 17:25:01 GMT -->

<identification>
  <ESN>1C7FBA7E010000A6</ESN>
  <Tag>4</Tag>
  <UnitType>Basalt</UnitType>
  <Version>3.16.1s Pre-release</Version>
</identification>
<Configuration>
  <smarts>
    <DataCushion>10000</DataCushion>
    <DataDir>\data</DataDir>
    <EasyMode>true</EasyMode>
    <MaxLogBytes>102400</MaxLogBytes>
    <PostEventSec>10</PostEventSec>
    <PreEventSec>5</PreEventSec>
    <PublishDebug>0</PublishDebug>
    <TempDataDir>NONE</TempDataDir>
  </smarts>
  <layout>
    <AltusEvtArchiver>
      <type>AltusEvtArchiver</type>
      <subscribesTo>EventRecorder_Output</subscribesTo>
    </AltusEvtArchiver>
    <AutoFileDelete>
      <type>AutoFileDelete</type>
      <subscribesTo>NOTHING</subscribesTo>
    </AutoFileDelete>
    <CommandConsole>
      <type>CommandConsole</type>
      <subscribesTo>NOTHING</subscribesTo>
    </CommandConsole>
    <DataIntegrator>
      <type>DataIntegrator</type>
      <subscribesTo>_dig1_1_RockFrontEnd_Output</subscribesTo>
      <subscribesTo>EventRecorder_Request</subscribesTo>
    </DataIntegrator>
    <EMailMsgSender>
      <type>EMailMsgSender</type>
      <subscribesTo>NOTHING</subscribesTo>
  </layout>
</Configuration>
</smarts>
</Configuration>
```

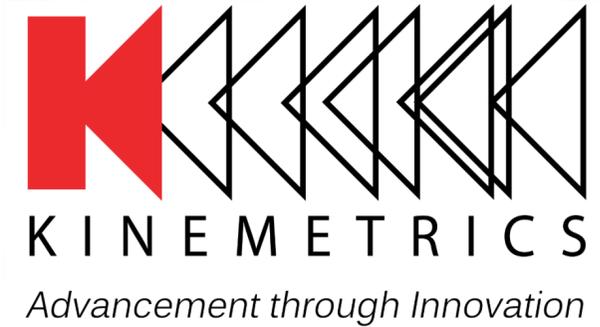
# Potential Changes

Possibly included in the 3.17 release

- Multiplexed ORB packets
- Other useful improvements?

# Resources

- support@kmi.com
- wiki.kmi.com
  - visitor, worldcup
- unitdata.kmi.com
  - Instrument and sensor data sheets



## Kinematics Datasheet Request Form

Product Type:

Serial Number 1:

Serial Number 2:

Serial Number 3:

E-mail Address:

Submit

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Office in Switzerland  
Training Center, Vienna – Austria  
Network Operation, Italy

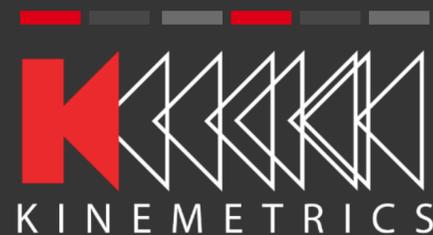


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# THANK YOU



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